## *COMPUTING THE OPTIMAL PRODUCTION RAPES IN A COMPLEX PRODUCTION SYSTEM*

## *Authors : Rafael RUIZ USANO Adolfo CRESPO MARQUEZ Dpto. de Organizaci6n Industrial y Gesti6n de Empresas*  **Escuela Superior de Ingenieros Industriales** *UNIVERSIDAD DE SEVILLA Avda. Reina Mercedes s.fn.,*  4~0~2 - *SEVILLA (SPAIN)*

#### *ABSTRACT.*

ਮੈਂਡ ਪਲੇਟੇ

*It is very well known that the setting of the optimal production rates in a complex production system is one of the most important and difficult decisions to be taken. This decision making process frequently seems to be an artisan job as it is necessary to take into account many influential factors simultaneously. In this paper we discuss the way of setting the optimal production rates, by applying optimization techniques and system dynamics methodologies. We study the effects of this approach on costs in* order *to minimize them and obtain good overall results, even for non-financial measurements. Simulation results are presented.* 

#### ~. *INTRODUCTION.*

*The use of System Dynamics to build simulation models is widely accepted mainly* due *(Coyle,* ~990) *to the speed, which one can model, the transparency of influence diagrams and its adecuacy in modelling real situations. A good number of applications have been developed since the appearance of Forrester's models on Industrial Dynamics (Forrester, 1964). At present we can consider the S.D. methodology as a conventional and powerful tool within which a huge scientific and professional community is actively working all over the world in the industrial dynamics field and developing new approaches to improve the results.* 

*In this paper we try to compute the production rates in a production planning system using an optimization model connected with the S.D. model. In section 2, we briefly explain the S.D. model used to reproduce the structure and behaviour of the production planning system. Section 3 shows the optimization model that interacts with the dynamic model* . *It computes the optimal production rates which are fed into the S.D. model. Section 4 describes the design of the proposed approach and the relationships between both models: s .D. and Optimization. Some simulation results are presented at the end of the paper with a short discussion on the advantages of the proposed mixed approach to modelling the system.* 

### 2 • THE SYSTEM DYNAMICS MODEL

*A basic production-inventory model is presented in*   $r$ iqure 1. In this model there are three levels which determine the *future-status of the system at any time:* 

- *-Customer's* orders *backlog: number of* orders *pending* to
- 
- **be shipped at the instant at the instant at the instant of the ins** 
	- *k. Depends on the production lead time. Inventories of finished products at the instant k.*

*The demand is taken as an exogenous variable*   $p$ olicies *developed* to *calculate the*   $rates$  and set up *behaviour of the system.* 

*Shipping a unit depletes both the backlog of customers* orders *and the inventory of finished products. The level of backlog is assumed* to *be a company's policy depending on the levels of the inventories of products.* 

*The most decision seems*  to *be the selection appropriate rates. important of the production* 

*In the model presented, the production rates for the next integration period* are *evaluated by checking the inventories (INV), demand forecasting (DF), and making sure that the rates computed* are *within the maximal production capacity (MPC).* 

*The demand forecasting* 



Ilustr. 1. Forrester's Diagram.

*will establish the desired inventory by considering a minimal inventory cover period (ICP)* . *Obviously, the production* rate *should be acceptable* to *match the discrepancies (DIS) between the current and the desired inventory within a required time (TAI).* 

**WIP** 

 $\mathbb{C}^{n\times n}$  , is fought to  $\mathbb{C}$ 

**Side Service** 

 $\mathcal{L}_{\mathrm{R}}$ 

#### *3.THE OPTIMIZATION HODEL*

*The production management tries always to coordinate the strategic and the· tactical planning. It therefore has to take into account the real cost structure and constraints of different types: financial, economical, technological, etc.* 

*With this modelling criterion, the production rates can be calculated by computing the optimal solution of a linear programming problem, at regular intervals. The objective function of this problem would incorporate the cost structure of the production system (Ruiz Usano, 1990).* 

MAX  $\sum_{i=1}^{i=N}$  (  $C_{i1}X_{i1}^{k} - C_{i2}X_{i2}^{k} - C_{i3}X_{i3}^{k}$  )

*The L.P. model is as follows:* 

*s. t. :* 

 $\leq DF^k$ <sup>~</sup>*DINk*   $\leq$  MPC<sup>k</sup> *= INVk*  <sup>~</sup>*0* 

 $i = 1, 2, \ldots N$ *k = 1, 2, ....* <sup>n</sup> (Number *of* products) *(Time)* 

*Subscripts:* 

*1 sales for the next period 2 inventories at the end of the next period. 3 production rates for the next period.* 

*Coefficients of the objective function:* 

*cil unit income*   $c_{i2}^{11}$  unit inventory holding cost<br> $c_{i3}$  unit production cost *ci3 unit production cost* 

*Right hand side values:* 



*4. COMPUTING THE OPTIMAL PRODUCTION RATES.* 

*In. most production planning system the calculation of the production rate is made on a heuristic basis (Forrester, 1964; Coyle, 1977)* , *as follows:* 

*PR =SMOOTHED DEMAND* + *K\*(DESIRED VALUE OF LEVEL VARIABLES* - *CURRENT VALUE)* 

*Where PR is the Production Rate and the variables are usually inventory, backlog, etc.* 

**FRATE Production Output**<br> **Rate** *is* normally *calculated as* a *delay of the entering Production Rate above (PRJ.* 

*Is this a good*  production rate?. *heuristic basis the answer could be. Why not?* 

*Can we make some progress setting the production rates in a different way? The answer should be: it depends on what objectives you are trying to achieve. In the*   $m$ *anagement criterion the setting of the production rates is one of the most important decision to be made.* 

*On the other hand we have powerful optimization techniques which we often*   $calculated$ *optimal decision variables in a rather isolated*  without taking *into account the dynamic and interacting environment of the production planning system.* 



planning Figure 2. S.D. - Optimization's Diagram.

# *Therefore, the basic*

*idea is to design an optimization model that computes the optimal production rates* , *with an objective function given by the system's manager and these are fed into the S.D. model.* 

そんきん こうきんせいかい あみ

*The S.D.-Optimization•s diagram is shown in Figure 2. As it can be seen a part of the system has been replaced by the optimization model. The arrows entering the optimization model are the values calculated by the S.D. model and fed into the optimization model in* order *to update the parameters it needs.* 

#### *5. SIMULATION RESULTS.*

*We show the results obtained by simulation of S.D.- Optimization approach. Figure 3 and 4 represent respectively the optimal production rates and the inventories for both products in the case study. Figure 5 reproduces the value taken by the objective function of the optimization model* 

An *important advantage of using this approach is the way of setting the values of decision variables. These variables are subject to the management criterion translated into the optimization model, in the framework of the whole system, which takes into account the continuous interaction of the system dynamics. In addition, this approach (Wolstenholme, 1990) can be*  used *to fit model results to actual observations for model validation.* 

*All the equations and the parameter's numerical values can be found in the Dynamo source list of the model provided in the Appendix.* 

#### *6. ACKNOWLEDGEMENTS.*

*We would like to thank Prof. M. Toro from the Department of Ingenieria Electr6nica, Sistemas y Automatica of the University of Sevilla for the substantial help given in the computer implementation of this work. All the DYNAMO programs were translated, automatically by the software designed byM. Toro, into language* "C" *running under MS/DOS.* 

## 7. *REFERENCES.*

*Coyle, R.G. 1977. Management System Dynamics. John Wiley-Sons.* 

*Coyle, R.G. 1990. System Dynamics* - *The Next Decade.* 

*Proceedings of the 1990 European Conference of S.D.: 19-26 Edit. by V. D'Amato and* c. *Maccheroni. Milan. Italy.* 

*Forrester, J.W. 1964. Industrial Dynamics. MIT Press.* 

*Ruiz Usano, R. 1990. Suboptimization and System Dynamics in a Production Planning System: A Mixed Approach. Proceedings of the 1990 European Conference of S.D.: 361-371 Edit. by V. D'Amato and* c. *Maccheroni. Milan. Italy.* 

*Wolstenholme, E.F. 1990. System Enquiry. A System Dynamics Approach. John Wiley-Sons.* 



*8. APPENDIX.* 

```
* *********************************************~***************************** * BASIC PRODUCTION-INVENTORY MODEL * 
 * *************************************************************************** 
 FNCTN MAXIMIZ(7,1,9) ROUTINE CALL FOR OPTIMIZATION<br>INSERT MODFOR MODULE WITH FOR'DEFINITIONS
 INSERT MODFOR MODULE WITH FOR'DEFINITIONS<br>DMNSN VRES(VAR) RESULTSVECTOR FROM OPTIMIZA
                               RESULTS VECTOR FROM OPTIMIZATION MODEL
 * *************************************************************************** 
 * LEVEL EQUATIONS 
L CART, K(ART)=CART, J(ART)+ (DT)* ( FCON, JK(ART) – SUMI, JK(ART)) BACKLOG<br>L. INV, K(ART)=INV, J(ART)+ (DT)* ( FPT, JK(ART) – SUMI, JK(ART)) BACKLOG
L INV.K(ART)=INV,J(ART)+(DT)*(FPT.JK(ART)-SUMI,JK(ART)) INV<br>L WIP.K(ART)=WIP.J(ART)+(DT)*(FP.JK(ART)-FPT.JK(ART)) WIP
 L WIP.K(ART)=WIP.J(ART)+(DT)*(FP.JK(ART)-FPT.JK(ART))
* *************************************************************************** 
* AUXILIARY EQUATIONS 
A D. K(ART) =TABLE(TDEM(*,ART), TIME K, 0, 200, 10) DEMAND DEMAND DEMAND FORECAST
A PRD.K(ART)=SMOOTH(D.K(ART), TAD)
A IDES.K(ART)=PRD.K(ART)*GCI 
A RETRASO.K(ART)=TABLE(TETRAS(*,ART),INV.K(ART)/PRD.K(ART),0,10,1)<br>A MCP.K(ART)=SMOOTH(1.8*D.K(ART),TAC)<br>MAX.CAPACITY
A MCP. K(ART) = SMOOTH(1.8*D. K(ART), TAC)A INVAGR.K=SUM(INV.K(*)) 
A WIPAGR.K=SUM(WIP.K(*))
A DINSAT.K(ART)=CART.K(ART)-SUMI.KL(ART) 
A TINV.K(ART)=WIP.K(ART)+INV.K(ART) 
A TINVAGR.K=WIPAGR.K+INVAGR.K 
* *********************************************~***************************** * FLOW EQUATIONS 
R FPT.KL(ART)=DELAY3(FP.KL(ART), LT(ART)) R FCON.KL(ART)=D.K(ART)
R SUMI.KL(ART)=CART.K(ART)/RETRASO.K(ART) 
INSERT MODOPT MODULE FOR THE MATRIX RIGHTHAND SIDE UPDATE 
* *************************************************************************** 
* CONSTANTS AND PARAMETERS 
P TAC=8 SEMANAS<br>P TAD=3 SEMANAS
P TAD=3
P GCI=3 SEMANAS
C LT(*)=0.4, 0.4 SEMANAS<br>P POND=0.8 80 %
P POND=0.8 80 %<br>
P TAI=1.5 SEMANAS
P TAI=1.5
* *************************************************************************** 
* TABLES 
T TDEM(*,DOS)=500,300,600,500,250,650,500,750,650,850,750,900,800,950^
   ,800,1000,900,1100,900,1200,1100 
T TDEM(*,UNO)=1000,750,1000,500,750,1250,1000,1000,750,500,1000,750,600,850^
   11000,1250,7501500,650,800,1000 
T TETRAS(*,UNO)=6,1,1,1,1,1,1,1,1,1,1,1
T TETRAS(*, DOS)=6, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
* *************************************************************************** 
* INITIAL CONDITIONS 
N CART(ART)=FCON(ART)
N INV(ART)=IINV(ART) 
I IINV(*)=2000,1500 
N WIP(ART)=D(ART)*LT(ART)
* *************************************************************************** * SIMULATION SPEC 
* SPEC LENGTH=200/DT=O.l/PRTPER=5/SAVPER=5/TINIC=O/TCAMB=200 
SAVE INV,WIP,CART 
SAVE D, PRD, IDES, RETRASO, MCP, INVAGR, WIPAGR, DINSAT, TINV, TINVAGR
SAVE FPT, FCON, FP, SUMI
```
 $\frac{d}{d\mu}$ 

 $\tilde{\mathcal{G}}$ 

 $\vec{r}$ 

单元/的



SAVE VRES,MAT,FP,A

MODFOR.DYN



 $\mathbb{R}^3$ 

 $\mu A \mathcal{E} = 4 \alpha \mathcal{E}_\mathrm{eff} + 8.73$ 

 $\sim 10^{11}$  and  $\sim$ 

 $\sim$ 

an Alban (Alba)<br>Tha san Francisco<br>Castrictic (Branch)<br>Castrictic (Branch)

Page 625

k.